

Embedded video pipeline

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ToC

- ▶ Uvod
- ▶ Vstup
- ▶ Zpracovani
- ▶ Vystup
- ▶ Profilovani
- ▶ Zaver

Uvod

- ▶ Prehravani videa je HW narocne
- ▶ Embedded systemy maji omezene HW prostredky
 - ▶ Nizka pametova propustnost
 - ▶ Nevykonny procesor
- ▶ Embedded systemy maji podpurny HW
 - ▶ Dedikovane en/dekodery videa
 - ▶ Ruzne jednotky na upravu video (rotace, scaling, ...)
- ▶ HW je potreba vyuzit efektivne
- ▶ Audio nebude (komplexita na jinou prednasku)

Video pipeline

Tri casti

- ▶ Vstup
 - ▶ Soubor
 - ▶ Kamera
- ▶ Zpracovani
 - ▶ Hardware
 - ▶ Software
- ▶ Vystup
 - ▶ Soubor
 - ▶ Display

Vstup

- ▶ Soubor je snadny (`open()` + `read()`)
- ▶ Kamera je slozitejsi
 - ▶ V4L2 subsystem
 - ▶ Media controller (komplexni kamery)
- ▶ Kamera v embedded systemech
 - ▶ Sensor (mimo SoC)
 - ▶ Camera IP (v SoC)

Sensor

- ▶ Snimac mimo SoC
- ▶ Muze mit ISP (konverze pixel formatu, 3A)
- ▶ Interface:
 - ▶ Parallel
 - ▶ MIPI CSI
- ▶ Pixel format
 - ▶ RGB (s ISP)
 - ▶ YUV
 - ▶ Bayer SRGB

Camera IP

- ▶ IP v SoC
- ▶ Prijima data ze sensoru
- ▶ Zapisuje data do RAM
- ▶ Muze umet konvertovat pixel format sensoru
- ▶ Muze umet dalsi speciality (predzpracovani)

V4L2

- ▶ Kernelove API pro praci s media zarizenimi
- ▶ Typicky kamera (vstup), M2M (zpracovani), ale i vystup
- ▶ V4L2 drivery pro kamery
- ▶ Common V4L2 kod pro spravu bufferu
- ▶ Buffery
 - ▶ mmap
 - ▶ dmabuf
- ▶ Nastroj v4l2-ctl
 - ▶ `v4l2-ctl -d /dev/video0 --stream-mmap \`
`--stream-count=1 --stream-to=/tmp/file.raw`
 - ▶ ffmpeg pro konverzi raw dat

Media controller

- ▶ API pro konfiguraci komplexnich kamer
- ▶ Komplexni kamera ma vice konfigurovatelnych casti
- ▶ Napr. zabudovana rotace obrazu, CSC, ...
- ▶ Viz media-ctl

V4L2 demo – alokace

```
1 int v4lfd = open("/dev/video0", O_RDWR);
2
3 struct v4l2_format fmt;
4 ioctl(v4lfd, VIDIOC_G_FMT, &fmt);
5
6 struct v4l2_requestbuffers rqbufs;
7 rqbufs.count = CONFIG_V4L2_BUF_COUNT;
8 rqbufs.type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
9 rqbufs.memory = V4L2_MEMORY_DMABUF;
10 ioctl(v4lfd, VIDIOC_REQBUFS, &rqbufs);
11
12 for (i = 0; i < CONFIG_V4L2_BUF_COUNT; i++) {
13     struct v4l2_buffer buf = { 0 };
14     buf.index = i;
15     buf.type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
16     buf.memory = V4L2_MEMORY_DMABUF;
17     ioctl(v4lfd, VIDIOC_QBUF, &buf);
18 }
19
20 int type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
21 ioctl(v4lfd, VIDIOC_STREAMON, &type);
```

V4L2 demo – dequeue/enqueue

```
1 struct pollfd pfd;
2 pfd.fd = v4lfd;
3 pfd.events = POLLIN;
4
5 poll(&pfd, 1, -1);
6 if (pfd.revents & POLLIN) {
7     struct v4l2_buffer buf = { 0 };
8     buf.type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
9     buf.memory = V4L2_MEMORY_DMABUF;
10    ioctl(v4lfd, VIDIOC_DQBUF, &buf);
11    int index = buf.index;
12
13    ...
14
15    memset(&buf, 0, sizeof(buf));
16    buf.type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
17    buf.index = index;
18    buf.memory = V4L2_MEMORY_DMABUF;
19    ioctl(v4lfd, VIDIOC_QBUF, &buf);
20 }
```

V4L2 demo – mmap

```
1 struct v4l2_buffer buf;
2 void *map;
3
4 for (i = 0; i < CONFIG_V4L2_BUF_COUNT; i++) {
5     memset(&buf, 0, sizeof(buf));
6     buf.index = i;
7     buf.type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
8     buf.memory = V4L2_MEMORY_DMABUF;
9     ioctl(v4lfd, VIDIOC_QUERYBUF, &buf);
10
11     map = mmap(NULL, buf.length,
12               PROT_READ | PROT_WRITE, MAP_SHARED,
13               v4lfd, buf.m.offset);
14     if (map == MAP_FAILED)
15         exit(EINVAL);
16 ...
```

Zpracovani

- ▶ Hardware – V4L2 mem2mem zarizeni
 - ▶ Chova se velmi podobne jako V4L2 kamera (jen ma dve fronty bufferu)
 - ▶ M2M zarizeni cte buffer z RAM na vstupu
 - ▶ M2M zarizeni implementuje transformaci
 - ▶ M2M zapisuje buffer do RAM na vystupu
 - ▶ Typicky rotace, scaling, CSC, en/dekodovani videa
 - ▶ Konfigurace pomoci V4L2 nebo media controller
- ▶ Kamera v embedded systemech
 - ▶ Softwarove implementace filtru (treba pomoci SIMD)

Vystup

- ▶ Soubor je snadny (`open()` + `write()`)
- ▶ Display je slozitejsi
 - ▶ DRM subsystem
 - ▶ fbdev emulace

DRM subsystem

- ▶ Kernelove API pro obsluhu zobrazovacich zarizeni, GPU, ...
- ▶ Sprava a konfigurace topologie a vystupu
- ▶ Sprava pameti a bufferu (vc. importu DMABUFu)
- ▶ Atomicke updatovani obrazu, ...
- ▶ libdrm – wrapper okolo DRM ioctl
- ▶ Buffer object (BO) – struktura okolo bufferu s datama

DRM demo – open

```
1  drmModeRes *resources;
2  drmModeConnector *connector = NULL;
3  drmModeEncoder *encoder = NULL;
4  int i, drmfd;
5
6  drmfd = open("/dev/dri/card0", O_RDWR | O_CLOEXEC);
7  resources = drmModeGetResources(drmfd);
8
9  for (i = 0; i < resources->count_connectors; i++) {
10     connector = drmModeGetConnector(drmfd, resources->connectors[i]);
11     if (connector->connection == DRM_MODE_CONNECTED)
12         break;
13     drmModeFreeConnector(connector);
14     connector = NULL;
15 }
16
17 for (i = 0; i < connector->count_modes; i++) {
18     drmModeModeInfo *current_mode = &connector->modes[i];
19     if (current_mode->type & DRM_MODE_TYPE_PREFERRED)
20         drmmode = current_mode;
21 }
```


DRM demo – open

```
1 for (i = 0; i < resources->count_encoders; i++) {
2     encoder = drmModeGetEncoder(drmfd, resources->encoders[i]);
3     if (encoder->encoder_id == connector->encoder_id)
4         break;
5     drmModeFreeEncoder(encoder);
6     encoder = NULL;
7 }
8
9 drmModeFreeResources(resources);
10
11 drmcrtc_id = encoder->crtc_id;
12 drmconnector_id = connector->connector_id;
```

DRM demo – framebuffer

```
1  uint32_t width, height, strides[4] = {0}, handles[4] = {0}, offsets[4]
2  const unsigned bo_attrs[] = { ... };
3  struct kms_driver *kd;
4  struct kms_bo *bo;
5
6  kms_create(drmfd, &kd);
7  kms_bo_create(kd, bo_attrs, &bo);
8
9  ...
10 kms_bo_map(...);
11 ...
12 kms_bo_unmap(...);
13 ...
14 kms_bo_get_prop(bo, KMS_HANDLE, handles);
15
16 drmModeAddFB2(drmfd, width, height, DRM_FORMAT_XRGB8888,
17              handles, strides, offsets, &fb_id, 0);
18
19 drmModePageFlip(drmfd, drmrtc_id, fb_id,
20                DRM_MODE_PAGE_FLIP_EVENT, &waiting_for_flip);
```

Import DMABUF

- ▶ V4L2 DMABUF jde exportovat a importovat primo do DRM
- ▶ Embedded GPU je typicky mem2mem zarizeni
 - ▶ Cte data z RAM, zapisuje data do RAM
 - ▶ Stejna RAM jako pouziva kamera, display, ...
- ▶ Je mozne importovat primo jako texturu do GPU

GBM

- ▶ libgbm – Generic Buffer Management
- ▶ Wrapper okolo alokatoru BO
- ▶ Spravu bufferu DRM zarizeni, hlavne GPU
- ▶ Soucast mesa3d (nicmene BSD, takze i soucast blobu)

GBM demo – alokace

```
1 static uint64_t modifiers[] = {DRM_FORMAT_MOD_LINEAR};
2 uint64_t *mods = modifiers;
3 int count = 1;
4
5 gbm_dev = gbm_create_device(drmfd);
6 gbm_surface = gbm_surface_create_with_modifiers(gbm_dev,
7         drmmode->hdisplay, drmmode->vdisplay,
8         GBM_FORMAT_XRGB8888, mods, count);
```

GBM demo – framebuffer

```
1  uint32_t width, height, strides[4] = {0}, handles[4] = {0}, offsets[4]
2  struct gbm_bo *bo;
3
4  bo = gbm_surface_lock_front_buffer(gbm_surface);
5
6  width = gbm_bo_get_width(bo);
7  height = gbm_bo_get_height(bo);
8
9  handles[0] = gbm_bo_get_handle(bo).u32;
10
11  drmModeAddFB2(drmfd, width, height, DRM_FORMAT_XRGB8888,
12               handles, strides, offsets, &fb_id, 0);
13
14  drmModePageFlip(drmfd, drmctxc_id, fb_id,
15                 DRM_MODE_PAGE_FLIP_EVENT, &waiting_for_flip);
```

V4L2 a DRM demo – export a import DMABUF FD

```
1 struct v4l2_exportbuffer expbuf;
2 expbuf.index = i;
3 expbuf.type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
4 ioctl(v4lfd, VIDIOC_EXPBUF, &expbuf);
5 /* expbuf.fd je FD DMABUFu */
6
7 ...
8
9 eglCreateImageKHR(
10     display, EGL_NO_CONTEXT, EGL_LINUX_DMA_BUF_EXT, NULL,
11     (const EGLint []){
12         EGL_WIDTH, fmt.pix.width,
13         EGL_HEIGHT, fmt.pix.height,
14         EGL_LINUX_DRM_FOURCC_EXT, DRM_FORMAT_YUV420,
15         EGL_DMA_BUF_PLANE0_FD_EXT, expbuf.fd,
16         EGL_DMA_BUF_PLANE0_OFFSET_EXT, 0,
17         EGL_DMA_BUF_PLANE0_PITCH_EXT, fmt.pix.width * 2,
18         EGL_NONE
19     });
```

Propustnost DRAM

- ▶ memcpy() spotrebovava DRAM bandwidth (viz Drepper <https://www.akkadia.org/drepper/cpumemory.pdf>)
- ▶ V4L2 M2M a GPU implicitne kopiruji
- ▶ Ostatni kopirovani je potreba eliminovat
- ▶ Zero-copy operace – bez neuzitecneho kopirovani
- ▶ Vyhledavani problemu, perf a HW DRAM countery

Propustnost DRAM – perf demo

```
1 $ perf list | grep ddr
2   ddrperf/activate_cnt/      [Kernel PMU event]
3   ddrperf/idle_cnt/         [Kernel PMU event]
4   ddrperf/read_cnt/         [Kernel PMU event]
5   ddrperf/time_cnt/         [Kernel PMU event]
6   ddrperf/write_cnt/        [Kernel PMU event]
7   mem:<addr>[/len] [:access] [Hardware breakpoint]
8
9 $ perf stat -a -e ddrperf/read_cnt/,ddrperf/write_cnt/ sleep 1
10 Performance counter stats for 'system wide':
11           5701736      ddrperf/read_cnt/
12           19513        ddrperf/write_cnt/
13      1.013295459 seconds time elapsed
14
15 $ perf stat -a -e ddrperf/read_cnt/,ddrperf/write_cnt/ sleep 1
16 Performance counter stats for 'system wide':
17           19361468      ddrperf/read_cnt/
18           6673730       ddrperf/write_cnt/
19      1.058049131 seconds time elapsed
```

Propustnost CPU

- ▶ Embedded CPU neoplyva vykonem
- ▶ Pozor na SW implementace ruznych konverzi
- ▶ Pokud neni zbyti, SW implementace pomoci SIMD
- ▶ SIMD: arm neon, ppc altivec, x86 mmx/sse
- ▶ GStreamer a ORC / ffmpeg a swx

Gstreamer

- ▶ Framework pro práci s multimedií
- ▶ Často se používá pro skrytí detailů media pipeline
- ▶ Implicitně nemusí optimálně využívat pipeline
- ▶ Demo gstreamer:

```
1 gst-launch-1.0 v4l2src device=/dev/video0 io-mode=dmabuf ! \  
2   v4l2convert output-io-mode=dmabuf-import \  
3     capture-io-mode=dmabuf ! \  
4   kmssink
```

Gstreamer videoconvert

- ▶ Element pro softwarovou konverzi video formátu
- ▶ Muze byt instanciovan implicitne
- ▶ Pouziva ORC pro SW akceleraci pomoc SIMD, pokud to jde
- ▶ Viz `GST_DEBUG="*:9"` a `ORC_DEBUG="9"`
- ▶ Casto lze nahradit lepsi konfiguraci pipeline / constraints:

```
1 gst-launch-1.0 v4l2src device=/dev/video0 io-mode=dmabuf ! \  
2   video/x-raw,format=YUY2 ! \  
3   v4l2convert output-io-mode=dmabuf-import \  
4     capture-io-mode=dmabuf ! \  
5   video/x-raw,format=RGBA ! \  
6   kmssink
```

Hledani problemu s CPU

- ▶ perf
- ▶ nahravani celeho systemu (potrebuje debug symboly)
`perf record -a -g sleep 5`
- ▶ `perf report --stdio`
- ▶ popr. `perf top` na real-time monitorovani

Demo – perf top

```
1 $ gst-launch-1.0 videotestsrc num-buffers=6000 ! \  
2   video/x-raw,format=I420,width=1280,height=720 ! \  
3   videoconvert ! \  
4   video/x-raw,format=BGRA ! fakesink
```

Overhead	Shared Object	Symbol
67.40%	libgstvideo-1.0.so,0,1801.0	[.] _backup_video_orc_convert_I420_BGRA
7.21%	libgstvideo-1.0.so,0,1801.0	[.] _backup_video_orc_chroma_down_v2_u8
3.56%	libgstvideotestsrc.so	[.] _backup_video_test_src_orc_splat_u32
3.53%	libgstvideo-1.0.so,0,1801.0	[.] _backup_video_orc_pack_I420
3.26%	libgstvideo-1.0.so,0,1801.0	[.] video_chroma_down_h2_cs_u8
2.07%	libgstvideotestsrc.so	[.] videotestsrc_blend_line
2.03%	libgstvideo-1.0.so,0,1801.0	[.] _backup_video_orc_pack_Y
1.01%	libc-2.31.so	[.] __memcpy_generic
0.92%	libgstvideotestsrc.so	[.] gst_video_test_src_smpte
0.47%	perf_5.9	[.] 0x00000000000f4f6c
0.34%	[kernel]	[k] _raw_spin_unlock_irqrestore
0.33%	[kernel]	[k] lock_is_held_type
0.31%	[kernel]	[k] lock_acquire
0.29%	[kernel]	[k] _raw_spin_unlock_irq
0.27%	libgstvideotestsrc.so	[.] video_test_src_orc_splat_u32
0.23%	libgstvideotestsrc.so	[.] videotestsrc_convert_tmpline
0.22%	libc-2.31.so	[.] strchr
0.19%	libgstvideotestsrc.so	[.] convert_hline_generic
0.17%	libc-2.31.so	[.] _int_malloc
0.15%	libgstvideotestsrc.so	[.] paint_tmpline_AYUW

For a higher level overview, try: perf top --sort comm,dsso

Demo – perf record (ORC backup)

- 1 \$ perf record -a -g sleep 5
- 2 \$ perf report --stdio

```
# To display the perf.data header info, please use --header/--header-only options.
#
#
# Total Lost Samples: 0
#
# Samples: 22K of event 'cycles'
# Event count (approx.): 7867169797
#
# Children      Self  Command      Shared Object      Symbol
# .....  .....  .....
#
#  94.02%    0.00% videotestsrc0:s  libc-2.31.so      [.] thread_start
#
#          |
#          |--thread_start
#          |start_thread
#          |0xffff880c1cac
#          |0xffff880c2640
#          |gst_task_func
#          |
#          |--94.01%--gst_base_src_loop
#          |
#          |---68.79%--gst_pad_push
#
:[]
```

Demo – perf record (ORC backup)

- 1 \$ perf record -a -g sleep 5
- 2 \$ perf report --stdio

```
chain_data_unchecked
|--gst_base_transform_chain
|
|--68.57%--default_generate_output
|
|--68.50%--gst_video_filter_transform
|
|--68.45%--gst_video_convert_transform_frame
|   convert_I420_BGRA
|   gst_parallelized_task_runner_run
|
|--68.44%--convert_I420_BGRA_task
|
|--68.41%--video_orc_convert_I420_BGRA
|
|--68.37%--_backup_video_orc_convert_I420
```


Demo – perf record (ORC SIMD)

- 1 \$ perf record -a -g sleep 5
- 2 \$ perf report --stdio

```
# To display the perf.data header info, please use --header/--header-only options.
#
# Total Lost Samples: 0
# Samples: 25K of event 'cycles'
# Event count (approx.): 8561629545
# Children      Self  Command      Shared Object      Symbol
# .....  .....  .....
```

Children	Self	Command	Shared Object	Symbol
87.44%	0.00%	videotestsrc:s	libc-2.31.so	[.] thread_start
				---thread_start
				start_thread
				0xffff9da40cac
				0xffff9da41640
				--87.43%--gst_task_func
				--87.42%--gst_base_src_loop

```
:#
```

Demo – perf record (ORC SIMD)

- 1 \$ perf record -a -g sleep 5
- 2 \$ perf report --stdio

```
_video_convert_transform_frame
48.37%--convert_I420_BGRA
  |--48.35%--gst_parallelized_task_runner_run
    |--48.35%--convert_I420_BGRA_task
      |--8.43%--0xffff9d2e8938
      |--7.38%--0xffff9d2e89c0
      |--6.23%--0xffff9d2e8948
      |--5.58%--0xffff9d2e899c
      |--4.98%--0xffff9d2e89ac
      |--4.22%--0xffff9d2e897c
      |--3.99%--0xffff9d2e895c
:[]
```

Zaver

- ▶ memcpy() je problem
- ▶ pozor na CPU cykly
- ▶ optimalni konfigurace pipeline je dulezita

Konec

Dekuji za pozornost